

Retrieval of Soil Moisture and Forest Biomass using CYGNSS Data and Artificial Neural Networks

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Introduction

- The possibility of estimating bio-geophysical parameters as soil moisture (SM) and forest biomass is of great relevance for many studies on carbon cycle and climate changes.
- Global navigation satellite system reflectometry (GNSS-R) could represent a valuable tool for this application.
- This study aims at assessing the **potential** of the NASA's Cyclone GNSS (**CyGNSS**) data for observing SM and biomass.
- As reference values for the comparison, the Vegetation Optical Depth (VOD) and SM derived from SMAP, as well as the aboveground biomass (AGB) from the GEOCARBON Global Forest map proposed in 2016 by Avitabile et al. have been considered.
- The results of the sensitivity analysis suggested exploiting the CyGNSS capabilities in estimating AGB and SM by setting-up prototype retrieval algorithms based on Artificial Neural Networks (ANN)

The study was carried out in the framework of the "GNSS Overland" project funded by ESA





- CyGNSS data collected over land on a global scale within a latitudinal range of approximately +/-38° have been downloaded from <u>https://podaac.jpl.nasa.gov</u>.
- The observables used for the analysis are the SNR, already contained in the Level 1 CyGNSS files, the calibrated SNR as proposed by Chew and Small (2018) and the Reflectivity as proposed by Clarizia et al. (2018).
- These parameters have been computed for the period April – August 2017 and re-gridded on the SMAP and Geocarbon grids for enabling the comparison.

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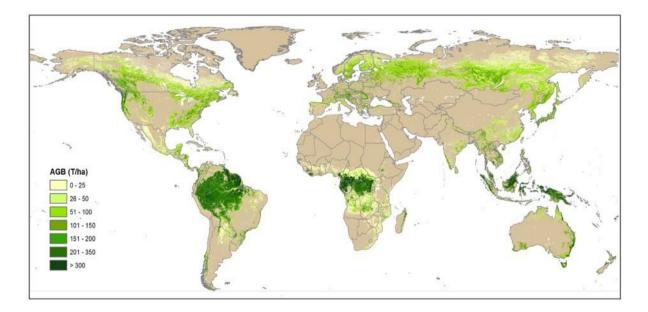
Reference data

SM and VOD :

- from SMAP L3 v.5 Radiometer global daily EASE-Grid data
- Soil Moisture [cm³/cm³]
- Vegetation Opacity (VOD)

AGB:

AGB data derived from the GEOCARBON Global Forest map proposed in 2016 by Avitabile et al. (www.geocarbon.net).



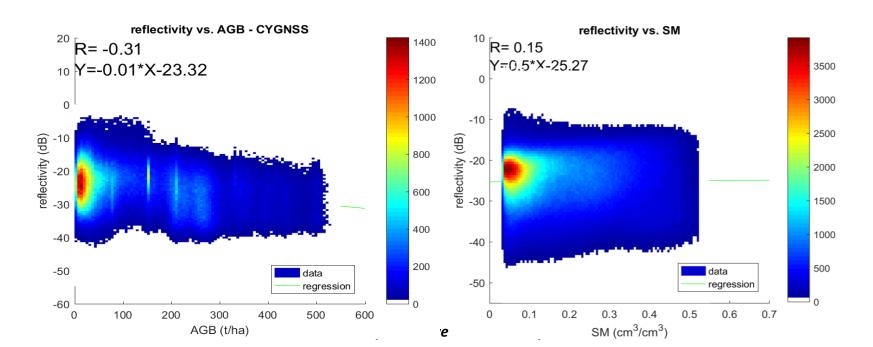
Sensitivity to SM, VOD and AGB

- The expected decrease of reflectivity when Biomass (both VOD or AGB) increases is confirmed (more details in the next presentation)
- A very slight increase whit SM was also found

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- SNR did not show any correlation to the target parameters
- ➤ Correlation is poor → need of advanced algorithms for the retrieval (ANN)





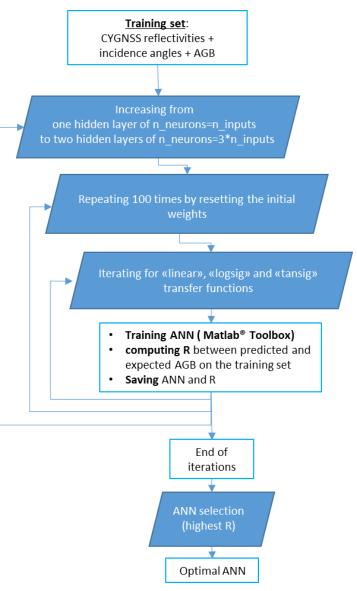
Addressing the retrieval

Implementing retrieval algorithms based on Artificial Neural Networks



ANN Architecture definition

- Multi-Layer Perceptrons ANN trained with the back-propagation (BP) learning rule
- Optimal ANN architecture (number of neurons and hidden layers) is defined iteratively for preventing overfitting and underfitting
 - □ Start: one hidden layer
 - n. neurons= n. inputs
 - □ Stop: three hidden layers
 - n. neurons= 4 x n. inputs
- Training repeated 20 times for each architecture, by resetting each time the initial weights.
- Training also repeated for each transfer function available (linear, tansig and logsig)
- Output is the "optimal" ANN for the given problem (best R).





CyGNSS vs. AGB

Retrieval of AGB Reference from Geocarbon

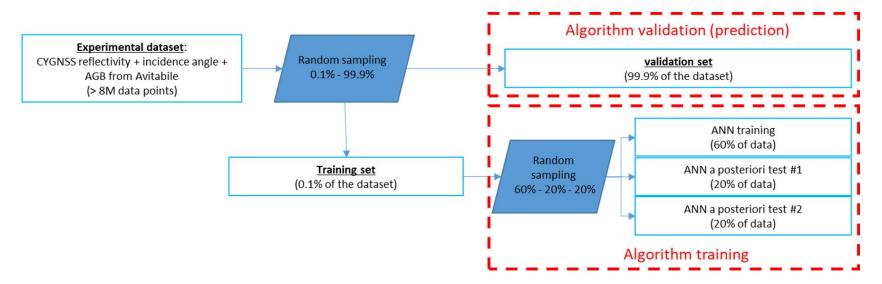
ANN training – CyGNSS vs. AGB

- Algorithm inputs are reflectivity and incidence from CyGNSS
- Output is AGB

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- Both CyGNSS and **AGB regridded** at 0.05° spacing ($\simeq 5$ Km) $\simeq 8$ M data points
- 0.1% of data considered for training the algorithm and the remaining 99.9% for validation.
- Training set further subsampled in 60%, 20% and 20% subsets: the first subset served for iteratively adjusting the ANN weights and connection strengths using BP; and the second and third subsets were used for validation and for having a posteriori test at each training iteration.

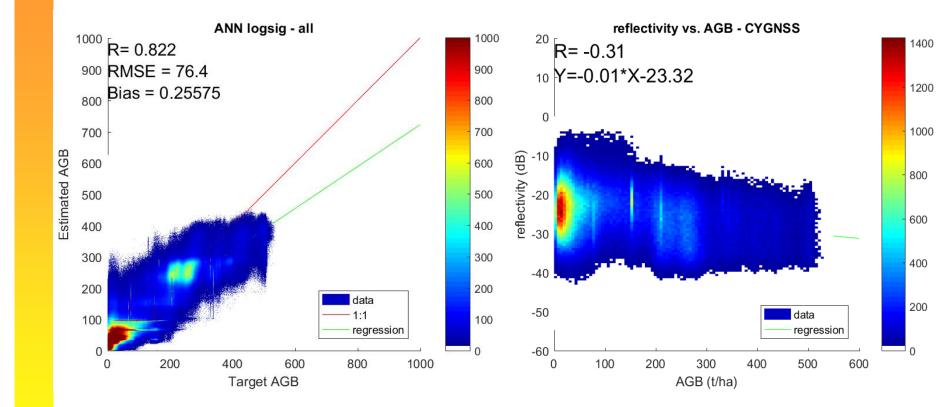


Algorithm validation

Validation on the 99.9% of data not involved in the training

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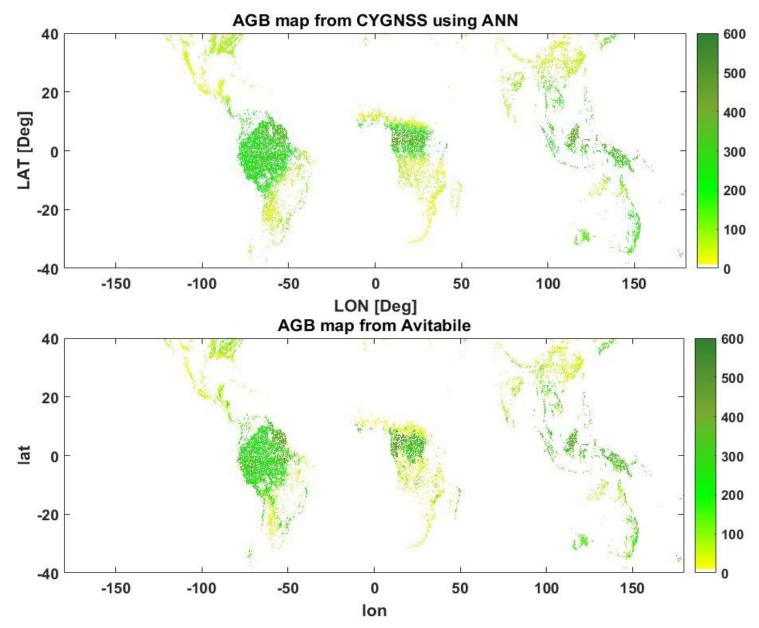


R=0.82 - RMSE=76.4 (t/ha)

CYGNSS vs GEOCARBON: AGB maps

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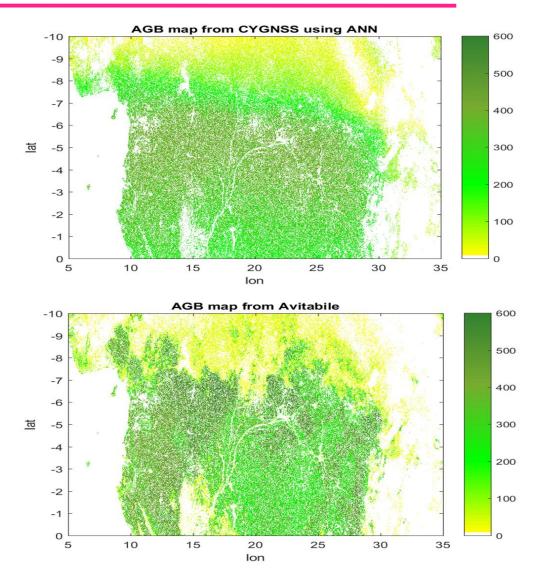




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CYGNSS vs GEOCARBON: AGB maps

- Quite promising result but ANN does not detect local patterns -> TBD
- Possibly due to the reference AGB: a «static» maps is not the optimal reference for comparison, moreover it has been obtained with older data (before 2014).





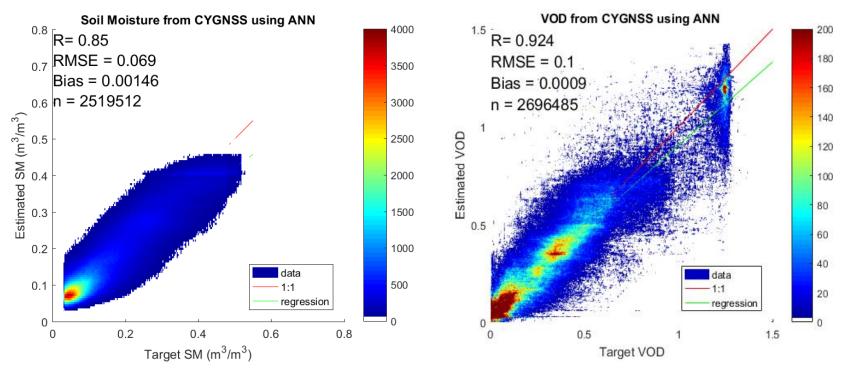
CyGNSS vs. SMAP

Retrieval of SM and VOD Reference from SMAP



CYGNSS vs. SMAP

- VOD and SM estimated from CYGNSS data using ANN
- CYGNSS and SMAP VOD/SM gridded on EASE GRID
- $\simeq 2,7$ M data Training on 1% of data, test on 99%
- Inputs: SNR, reflectivity and angle from CyGNSS + lat/lon
- Output: VOD or SM



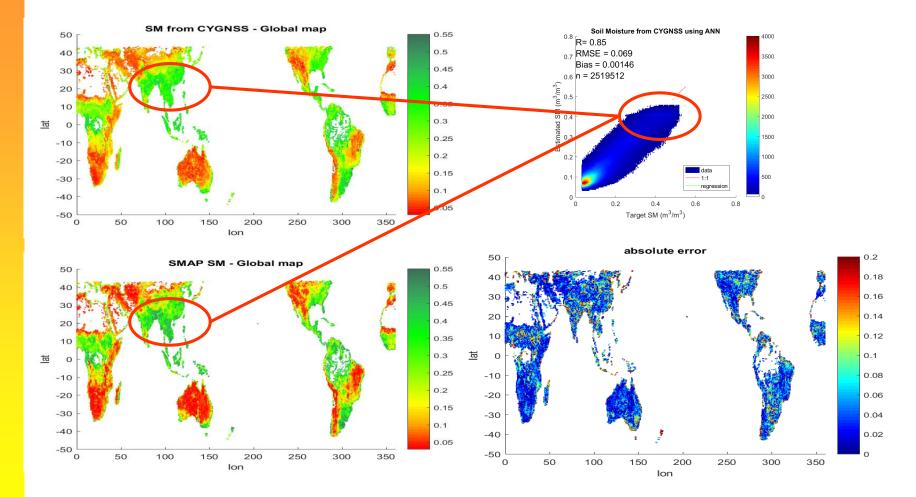
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CyGNSS vs. SMAP SM: average maps

ANN tends to slightly underestimate the higher values

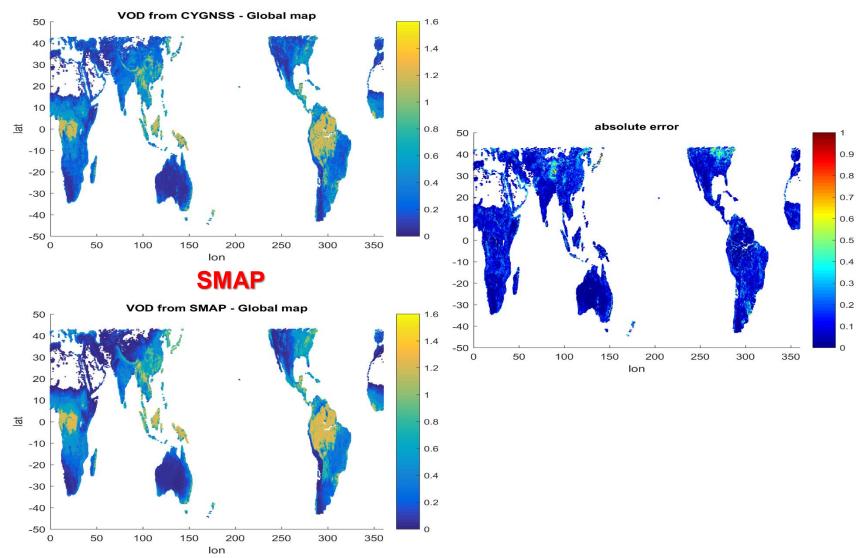




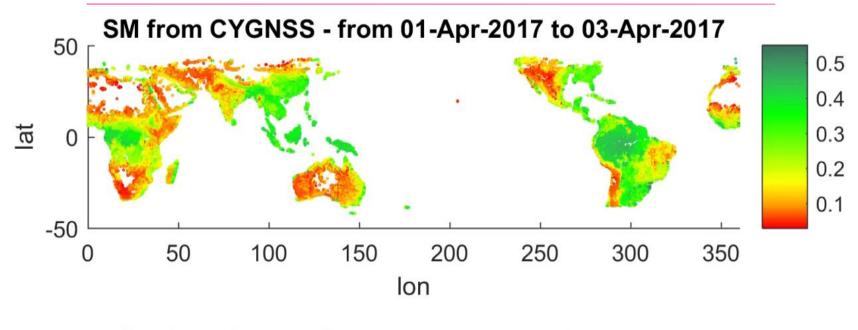
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CyGNSS vs. SMAP VOD: average maps

CyGNSS

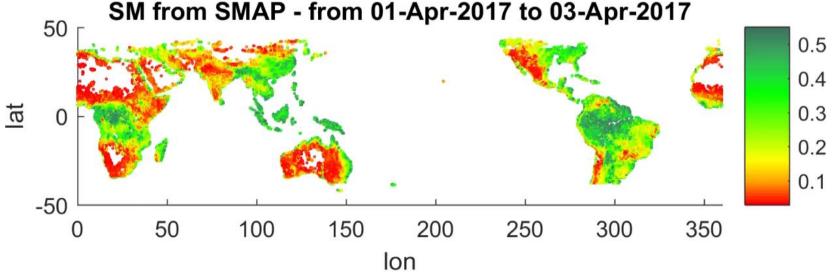


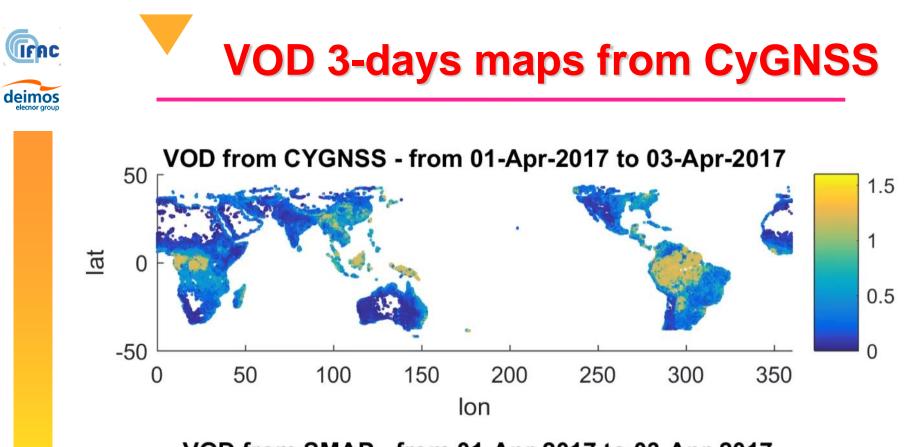
SM 3-days maps from CyGNSS

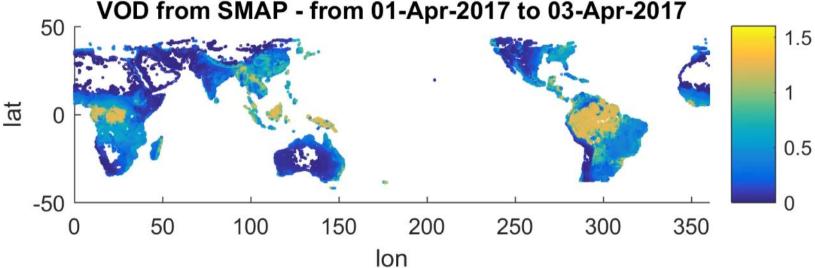


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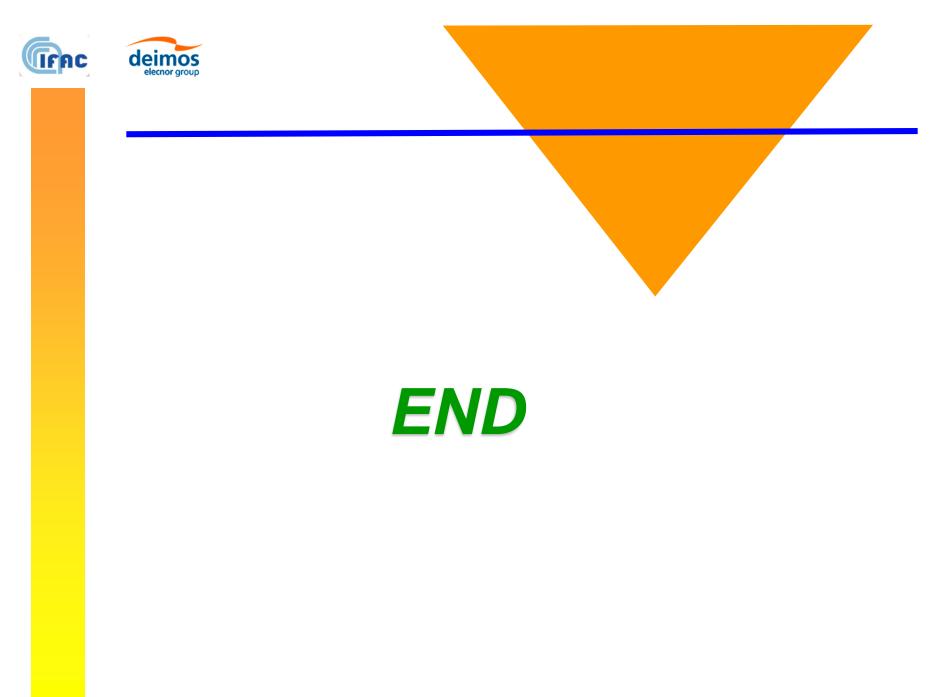






Some conclusions

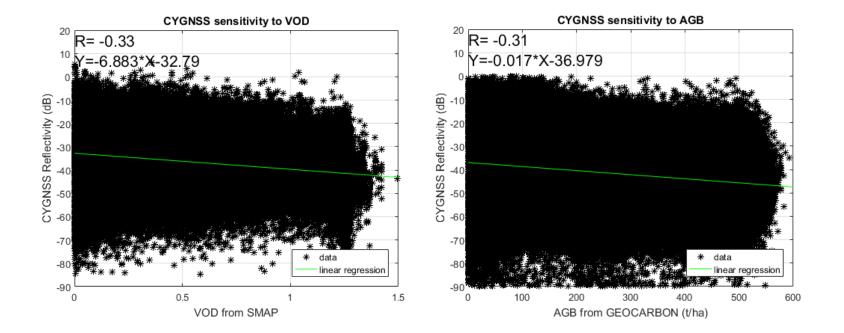
- CYGNSS seems able to catch the Soil Moisture and Biomass behaviors: retrieval is feasible provided that advanced algorithms (e.g. ANN) are used.
- Retrieval exercises returned similar results (0.82<R<0.92 in all cases)
- Reflectivity seems the most suitable parameter for the retrieval on land, SNR does not add much (more in the next presentation)
- Global retrievals have to be better exploited since the «static» map (AGB) is not the optimal reference for comparison
- In this respect SM and VOD from SMAP seem more adequate; however, are both derived from another L- band sensor, not from direct measurements.
- The prosecution of this study will consider using other datasets and involving more CyGNSS observables
- The possibility of using CyGNSS in synergy with other satellite sensors (SAR, MW radiometers, optical) will also be exploited



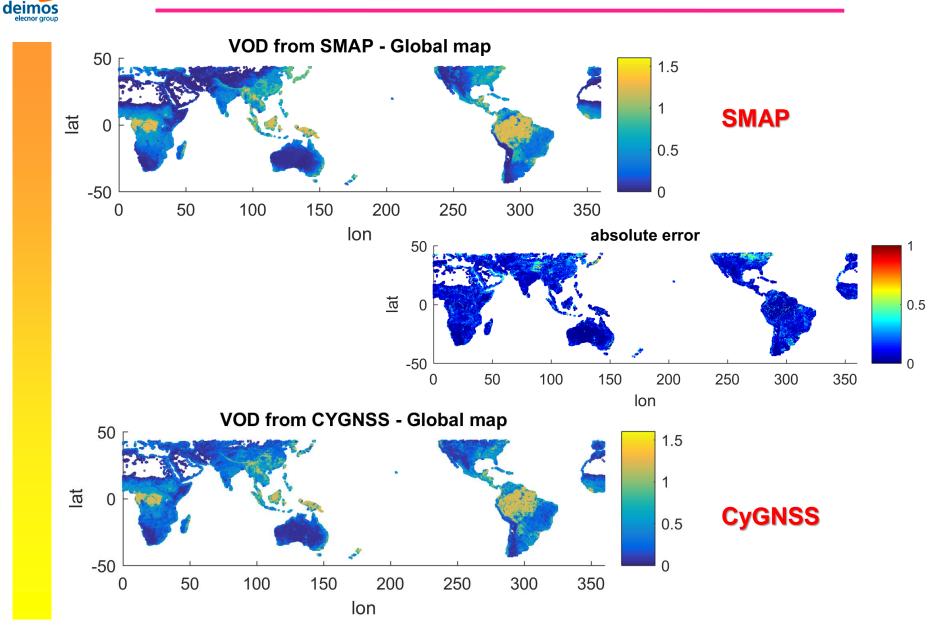


Previous results: Global analysis

- One year of CYGNSS data (2017)
- CYGNSS vs. SMAP VOD (R~-0.31)
- CYGNSS vs. AGB from pantropical map (R~-0.31 slope -0.02 dB*t/ha)



CyGNSS vs. SMAP VOD



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